Comparative Study on Flexible Link Aerator Using Arduino Programming and Dissolved Oxygen Meter

Fatin Farhana Anuar, Badrul Aisham Md Zain* and Najib Al-Shaibani

Advanced Dynamic Control Research Group (ADCARe) Faculty of Mechanical Engineering & Manufacturing Universiti Tun Hussein Onn Malaysia (UTHM), 86400 Parit Raja, Batu Pahat, Johor, Malaysia

Received 18 September 2017; accepted 19 April 2018, available online 4 August 2018

1. Introduction

This research is about the control motor operation by using Arduino into the flexible link aerator for controlling the dissolved oxygen in water of prawn pond. Aquatic living requires several properties to surviving. Generally, there need a suitable pH level, ammonia and dissolved oxygen. The quality of water is important because it can lead to the disease or die. The increasing of pH level, ammonia and dissolved oxygen can reduce the productivity [1]. The pH level, ammonia and dissolve oxygen need to maintain suitable to the aquatic living needed.

The aquatic lives might have the problem to obtain suitable dissolved oxygen in water and by using aerator system. It will develop dissolved oxygen automatically. The aerator system only helps to generate the dissolved oxygen then the Arduino is added for controlling the rate of dissolved oxygen in prawn pond. The volume of dissolved oxygen in water for aquatic lives is the parameter that needed to be controlled by Arduino. The flexible link aerator will undergo to fabrication process of improving the motor operation with Arduino. The value of dissolved oxygen in water will be measured for finding the rate of dissolved oxygen for aquatic lives. The experiment processes will start by analyzing the improvement to this new flexible link aerator.

By using Arduino, the flexible link aerator will develop the dissolved oxygen automatically according to the rate of dissolved oxygen for aquatic living. The aerator will undergo the improvement process and experiment to make sure the prototype operates as a flexible link aerator controller of dissolved oxygen in water.

2. Literature Review

2.1 Flexible Link Aerator

It is the operator that acts as an aerator by using flexible link to generate dissolved oxygen as in Figure 1. After
that, the flexible link moves from the water surface by the DC motor to generate the bubbles on the water to measure the dissolved oxygen by the developed Arduino system. The flexible link only soaks to the water surface. It is similar to the paddlewheel on producing waves and bubbles for increasing dissolved oxygen in water.

From several types of aerator, it shows that flexible ink aerator produces higher dissolved oxygen in water as shown in Table 1[2].

Table 1: Standard Oxygen Transfer Efficiency of the Basic Type of Aerator [2]

<table>
<thead>
<tr>
<th>Type of Aerator</th>
<th>Average Oxygen Transfer Efficiency (kgO₂/kWhr)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Flexible link aerator</td>
<td></td>
</tr>
<tr>
<td>with circle holes</td>
<td>2.70</td>
</tr>
<tr>
<td>Flexible link aerator</td>
<td></td>
</tr>
<tr>
<td>without circle holes</td>
<td>1.84</td>
</tr>
<tr>
<td>Propeller aspirator pump</td>
<td>1.58</td>
</tr>
<tr>
<td>Vertical pump</td>
<td>1.28</td>
</tr>
<tr>
<td>Paddlewheel</td>
<td>1.29 – 2.75</td>
</tr>
<tr>
<td>Pump sprayer</td>
<td>0.9 – 1.9</td>
</tr>
<tr>
<td>Diffused air</td>
<td>0.7 – 1.2</td>
</tr>
</tbody>
</table>

2.2 Dissolved Oxygen

Aquatic lives depend on dissolved oxygen for survival. Lack of dissolved oxygen will affect their life. They either face death or leave the area to find a better place. Dissolved oxygen concentration is influenced by many aspects such as water turbulence or wave action and the amount of oxygen used by aquatic lives [3].

Water temperature and atmosphere pressure effect the capacity of water to hold dissolved oxygen. It can drop due to weather and dissolved oxygen can increase while raining, and at night. Better quality of water depends largely on the amount of oxygen the water can hold by testing the dissolved oxygen for healthiness of the aquatic lives.

2.3 Arduino

The proposed Arduino controller introduced into this project consists of simple implementation control system compared to other controllers [4]. Arduino has input and output process in which it will receive the input from any surrounding situation such as sensor and it will analyze the problem according to the range given then transfer the information to the software and it appears as output for giving the solution for the occurring problem. By referring to the other experiment it also can develop a single phase back to back converter using voltage closed loop feedback with the ability of the Arduino as a low microcontroller to control the gate signal of power [5].

The important key of Arduino is it consists of microcontroller as it has the processor and memory to control any tool by simulating the input and output to produce the desired solutions from problems [6]. It will produce a variety of information such as movement towards robotic machine to operate according to the desired instruction.

Arduino can also be in automated mode from software monitoring to any controller appliances to respond to any signal and related sensor [4]. The Arduino can be communicated with software running on computer for analysis [7].

Machines are usually involved in motor system to produce movement such as in vehicles. Basically, motor is a device for producing energy either electric or mechanical. Motor should be controlled to avoid other system from damage. The motor selection should have high torque which is 12volts 4amp with 3.2Nm of maximum torque.

2.4 PID controller

The PID controller has several important functions and provides feedback and has the ability to eliminate steady state offset through integral action and can anticipate the future of derivative actions [8] [9]. PID controller is an important ingredient of a distributed control system.

Practically, PID controller is created today based on microprocessors. It has the opportunities to provide additional features like automatic tuning gain scheduling and continuous adaption. Auto tuning means that the controller parameters are tuning automatically on demand from an operator or an external signal. The control value provides feedback and has the ability to eliminate steady state offset through integral action and can anticipate the future of derivative actions [8] [9]. PID controller is an important ingredient of a distributed control system.

By using Zeigler-Nichols tuning method it will determine the PID controller parameter referring to tuning table [9].

Table 2: Tuning of PID controller Parameter according to Zeigler-Nichols Tuning by using step response methods [9]

<table>
<thead>
<tr>
<th>Controller</th>
<th>K_p</th>
<th>T_i</th>
<th>T_d</th>
</tr>
</thead>
<tbody>
<tr>
<td>P</td>
<td>1/α</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PI</td>
<td>0.9/α</td>
<td>3L</td>
<td></td>
</tr>
<tr>
<td>PID</td>
<td>1.2/α</td>
<td>2L</td>
<td>L/2</td>
</tr>
</tbody>
</table>

3. Methodology

The methodology is of developing the concept of designing to control the flexible link aerator. Designing the flexible controller link aerator will consist of Arduino system, and PID controller.

3.1 Concept Generated

The basic concept for this project is the flexible link aerator operated and control of the dissolved oxygen. For controlling the dissolved oxygen, it consists of Arduino as a controller. For controlling the flexible link by DC motor system, the motor will be attached to Arduino to control the parameter. The information that Arduino receives from sensor will give the instruction to motor for the flexible link aerator as shown in Figure 2.
3.2 Arduino
The block diagram of the project and design aspect of independent modules are considered as in Figure 3 [10].

3.3 The Schematic Diagram of Arduino system
The schematic diagram of Arduino System is considered as shown in Figure 4.

3.4 The Designing of Arduino Programming
Arduino will be installing the software for controlling the system. The flow chart of the system is as shown in Figure 5. From Arduino program which has been installed, there will be analysis of the information on sensor detected. The information will be analyzed for controller of the motor operating on adjusting the dissolved oxygen value.

3.5 Designing the Experiment
For conducting the experiment, the procedure is as shown in Figure 6. The experiment was set up on model tank with different quantity of water as a parameter to be measured. The model tank was filled with 8 liters, 12 liters and 16 liters of water for measuring the dissolved oxygen to be controlled. The Arduino programming had been uploaded for controlling the dissolved oxygen. The Arduino was operated based on the level on Arduino which was between 18.0% O₂ and 20.0% O₂ to operate the flexible link aerator.

3.6 Control Parameter
The parameter measured was the dissolved oxygen value of controlling the flexible link aerator through motor system. The rate of dissolved oxygen was between 18.0% O₂ and 20.0% O₂. From the previous research, the ideal dissolved oxygen is 18.0% O₂.
Fig. 6: Experimental Procedure

The average dissolved oxygen level by using Arduino programming is \( \text{18.18 } \% O_2 \) and \( \text{17.77 } \% O_2 \) is the value of average dissolved oxygen obtained from Dissolved Oxygen Meter.

4.1 Analysis of Experiment

The experiment was conducted by using different amounts of water through the experiment. 8 liters, 12 liters and 16 liters. The model tank was filled with water with initial dissolved oxygen level of \( \text{17.8 } \% O_2 \) and the initial temperature of \( \text{28.1 } \degree C \). The desired range of dissolved oxygen is between \( \text{18.0 } \% O_2 \) and \( \text{29.0 } \% O_2 \).

Based on the experiment of comparing the value of dissolved oxygen between Arduino and Dissolved Oxygen Meter without operating the motor of flexible link shows that there is difference which is \( \text{18.18 } \% O_2 \) and \( \text{17.77 } \% O_2 \) because different types of sensor were used in Arduino.

From the experiment, it can be seen that for 8 liters of water, the dissolved oxygen value is higher than 12 liters and 16 liters of water. The value of dissolved oxygen for 8 liters of water based on Dissolved Oxygen Meter that gives the average value within 30 minutes of the experiment is \( \text{22.42 } \% O_2 \). The dissolved oxygen meter shows an average value of dissolved oxygen by using Dissolved Oxygen Meter of \( \text{21.48 } \% O_2 \) and \( \text{21.01 } \% O_2 \) respectively which is lower than the 8 liters of water dissolved oxygen value. The average value of dissolved oxygen for 12 liters of water is \( \text{23.79 } \% O_2 \) and \( \text{22.34 } \% O_2 \) for 16 liters of water show that it is lower compared to the 8 liters of water dissolved oxygen value.

The initial readings of dissolved oxygen for 8 liters of water is higher than 12 liters of water which are \( \text{29.1 } \% O_2 \) and \( \text{17.9 } \% O_2 \). While for 16 liters of water, the reading got lower dissolved oxygen due to the higher the amount of water required in higher dissolved oxygen. For PID controller system, the set up value on Arduino programming is automatic. The PID set point will adjust automatically based on the
formula set in Arduino programming. From the experiment, it gives almost the same reading of dissolved oxygen for each volume of water because the PID controller programming had been set on Arduino.

5. Conclusion
The conclusion is two objectives of this research had been achieved. The experiment had been conducted to fulfil the objective requirement. The concept of controlling the dissolved oxygen level by using Arduino programming is to maintain the quality of water for aquatic lives such as tiger prawns.

The first objective to generate dissolved oxygen of flexible link aerator by using Arduino is achieved. Based on the experiment conducted, the value of dissolved oxygen for different volume of water shows that the higher the volume of water the lower the dissolved oxygen value. The experiment was conducted at the same area of water but with difference in the volume of water. The higher initial reading is at 8 liters of water which is 22.42 %O₂, compared to 16 liters of water which is 21.01 %O₂. It means that the flexible link needs to adjust the dissolved oxygen value if the volume increases.

The second objective is to implement the PID controller of controlling the flexible link aerator. The PID controller is used in Arduino programming to control the motor operation. PID controller it already on Arduino programming and connected with potentiometer for adjusting. The Arduino programming will adjust the value based on the potentiometer value set up. The value of set point, input, and output value for PID controller are set on the Arduino programming to operate the programming according to the formula. The recommendation is replacing the Conductivity water sensor with dissolved oxygen probe, which can give more accurate value of dissolved oxygen. The Electrical Conductivity Water Sensor for dissolved oxygen could also be replaced with the Analog Electrical Conductivity Meter with temperature compensation. The analog electrical conductivity meter can give out more accurate reading with temperature compensation. The Radio Frequency (RF) system for the operation of flexible link aerator could also be operated.

Acknowledgement
The authors would like to acknowledge the financial support received from the Research Management Centre (RMC) Universiti Tun Hussein Onn Malaysia (UTHM) under the Tier 1 Research Grant Scheme (Code H242).

References